

# Development Along with Design of an Independent Riding Reaper Device

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**Abstract-** Harvesting is the collection of mature crops from the field. A harvesting procedure involves cutting, installation, collecting, transferring, and then stacking the cut produce. Mechanization of harvesting operations is critical to lowering harvesting costs, crop production costs, crop loss, turnaround time, weather risk, and increasing benefit through proper technology. To achieve the desired purpose, a manually operated reaper machine is created and developed to assist farmers by lowering the cost of crop cutting and collection in the field while achieving the best efficiency possible within the limits. Research technique is a set of acts or procedures that must be completed in order to do research properly, as well as the intended sequence of these steps. Identify the problem statement. Studying the current design of the reaper machine Review the literature. Product development general design process steps for reaper harvester's machine include planning, concept development, system-level design, detail design, testing and refining, and product ramp-up. In this step, the material properties are defined based on design. To simulate the reaper machine using Catia software, Prototyping, testing for validation, Interpret and report. Material is chosen based on the strength requirements of the different parts of the Reaper machine. The machine is built with locally accessible materials. This self-propelled reaper moves at a forward speed of 2.54 m/s. The cutting bar measures 120 cm in length and the bundling mechanism is dropped. The field capacity is 0.306 ha/hour, respectively. The needed manpower for harvesting one hectare of wheat and rice reaper harvesting field operation is two man-hours per ha. The amount of fuel required to completely fill the tank after harvesting the plot was measured to determine the amount of fuel consumed for reaping the test plot, which was 1.17 l/h.

**Keywords-** harvesting, reaper machine, mechanization

## I. INTRODUCTION

Agriculture now plays a vital role in countries such as Ethiopia. Wheat and rice are significant crops and staple foods for millions of people, and they are farmed in many countries throughout the world, including ours. Harvesting crop is an important field

operation involving the collection of prepared wheat and rice crops from the fields. The collecting operation involves cutting, laying, and gathering, transferring, and stacking the removed produce. Harvesting methods utilized include hand harvesting (traditional harvesting) and automated harvesting.

### **1. Traditional Harvesting Involves Hand Mowing Using Sickles**

Crops are usually harvested manually. Major cereals, pulses, and oilseed crops are harvested with sickles, while tuber crops are reaped with a country plough or shovel. All of these traditional approaches are tedious and time-consuming.

### **2. Mechanical Harvesting is a Modern Mowing Approach that Uses a Machine**

The timing of harvest is critical. During harvesting season, rainfall and storms are frequent, inflicting significant damage to standing crops. Rapid harvest allows for an additional day of field preparation as well as earlier planting of the next crop. Machines can help harvest crops at the correct stage of ripeness, reducing drudgery and operation time. Considering this, farmers are accepting improved harvesting gear, equipment, and combines.

Mechanized agriculture is the process of deploying agricultural machinery to automate agricultural tasks, resulting in increased farm worker productivity. In modern times, powered machinery has replaced numerous jobs that were previously performed by manual labor or working animals such as oxen, horses, and mules. The history of agriculture includes numerous examples of tool use, such as the plow. Mechanization is the use of an intermediary device between the power source and the work. This intermediate device typically converts motion from rotary to linear or gives some sort of mechanical advantage, including speed increase or decrease or leverage. Tractors, trucks, combine harvesters, airplanes (crop dusters), helicopters, and other vehicles are commonly used in modern mechanized agriculture. Until the eighteenth century, most grains were harvested using a sickle or scythe. In the nineteenth century, mechanized reapers were invented to chop and windrow grain for field drying. A reaper is a wheat and rice harvesting machine that reaps crops and gathers them manually. There are numerous kinds of horizontal conveyors reapers readily accessible, including manually driven, self-propelled, tractor front mounted, and self-propelled tying reaper. Reapers are used to harvest crops primarily at ground level. It consists of a crop-row divider, a

cutter bar assembly, and feed and transporting equipment. Reapers are characterized based on crop conveyance, as follows:

#### **Vertical Conveying Reaper Windrower**

This machine cuts crops, transports them vertically to one end, and evenly distributes them on the ground. There are three types of reaper-windrowers available: self-propelled walking, self-propelled riding, and tractor-mounted.

Horizontal transporting reapers include crop partitions, crop collection reel in, cutter bar, and horizontal conveyor belt. They cut the crop, transport it horizontally to one end, and drop it on the ground in a head-tail method. It's compatible with wheat, rice, soybeans, and gram.

#### **Bunch Conveying Reapers**

Identical to horizontal conveying reapers, but cut crop is collected upon a platform and discharged to the ground as a bunch using a hand lever.

#### **Reaper Binder**

This kind of reaper's cutting machine can be either disc or cutter bar. After cutting, the crop is transported vertically to the binding mechanism and then released to the ground in the form of bundles. Reaper binders are appropriate for rice and wheat.

## **II. LITERATURE REVIEW**

This chapter discusses previous research on the performance of harvesting operations, and how mechanization is critical to reducing harvesting costs, crop production costs, crop loss, turnaround time, weather risk, and increasing benefit through appropriate technology. Crop harvesting is a major aspect of agricultural mechanization; it is the act of removing mature crops from the field. The harvesting operation involves slicing, laying, gathering, transferring, and stacking the cut produce. Harvesting methods utilized include traditional and mechanical harvesting. Product development general design process steps for reaper harvester's machine include planning, concept development, system-level design, detail

design, testing and refining, and product ramp-up. In this step, the material properties are defined based on the design.

### 1. Design and Develop a Reaper for Harvesting

(Devani and Pandey, 1985) Devised and built a vertical conveyor belt windrower to harvest wheat crops. The study found that the field capacity for 1.6 m wider units was 0.269 ha/h, whereas for 2.09 m wide units it was 0.337 ha/h. The operating costs of tractor and power tiller models were 20 to 30% less compared to the traditional manual approach.

(El-Sahrighi et al. ,, 1992) Created a front-mounted reaper. The design features included a flat belt mechanism that conveys the crop to the side of the machines. a strengthened cutter bar star wheel assembly to reduce clogging, a bevel gear drive for power transmission, a strong frame, a header provide design that does not dig into the soil, and the ability to convert the flat belt conveyor drivers to chain without frame modification.

(J Prasad et al. ,, 2001-2002) Developed a self-propelled riding reaper windrower powered by a small diesel engine. In a test of four wheat crop varieties, the mean values of plant height, effective field capacity, fuel consumption, and total machine loss were 84.6 cm, 0.336 ha/h, 1.35 l/h, and 0.610%, correspondingly.

(D.N Sharma and S. Mukesh, 2010) Conducted research on the design of self-propelled vertical conveyor reapers and tractor-powered vertical conveyor reaper harvesting equipment.

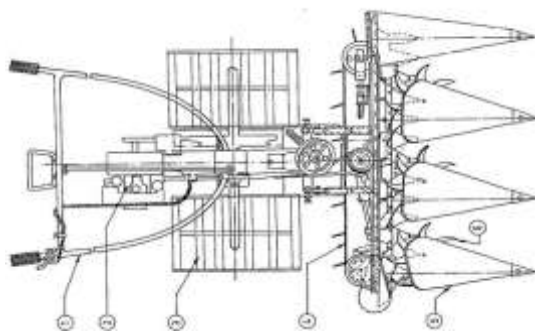


Figure 1: Self-propelled vertical conveyor reapers

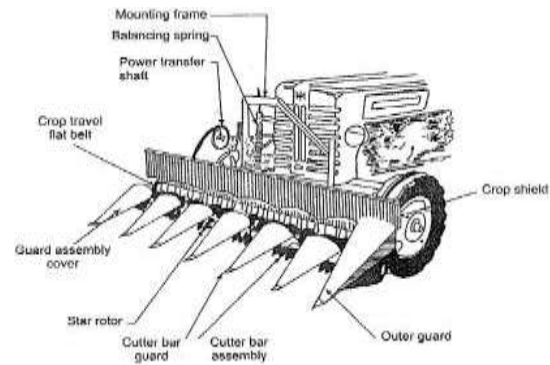


Figure 2: tractor operated vertical conveyor reaper

### 2. Comparing Field Performance of Different Reaper Machines

- (El-Sharabasy, 1997) Tested four different equipment (small combine harvester, power reaper, self-propelled mower, and rear mounted mower) in wheat and rice fields. He discovered the followings:-
- The tiny combine harvester resulted in a minimum grain loss of 1.66%.
- Self-propelled mowers showed the highest efficiency (78.04%).
- Tractor powered reaping machines produced a maximum field efficiency of 1.64 fed/h.
- Harvesting with a self-propelled lawnmower and threshing with a stationary thresher resulted in a minimum energy of 25.38 wk./fed.

### 3. Evaluation of Reaper Machine Performance in the Field

(Ni Ni Aung, Win Pa Pa Myo, and Zaw Moe Htet, 2012) Analyzed the field effectiveness of a vertical conveyor paddy reaper. The reaper's actual field capacity was 0.24 ha/hr, with a field efficiency of 92% and an average operating speed of 2.18 km/h. (Mahrous, tested and evaluated rear mounted mower, 1995) Examined and assessed a horizontal flat conveyor belt to increase the efficiency of a rear-mounted mower. The mower was run on a wheat crop at forward speeds of 3, 4, 5, and 6 km/h. The created rear-mounted mower had a standard field capacity, field effectiveness, cutting efficiency, and cost needs of 1.18 fed/h.

According to (Habib, Azzam and Khattab, 2001) , the parameters affecting the cutting process include the cutting tool, machine characteristics,

and plant material properties. They also mentioned the amount of energy consumed throughout the harvesting procedure.

According to (Sahar, Design of a harvester appropriate for Egyptian Agriculture, 1988), the usage of a large-scale machine is improper for the following reasons: - it requires extensive technical skill for operation and maintenance, as well as a significant investment. Low field efficiency occurs on small holdings, and straw losses are severe in irregularly furrowed soils. Small machines are suitable for small holdings with low capital requirements and limited technical operations and maintenance skills.

(Prof. P.B. Chavan, Prof. D.K. Patil, and Prof. D.S. Dhondge, 2015), 2015) Discovered that reapers tend to be selected based on the farmer's land holding; the larger the agricultural holding, the tractor-operated vertical conveyer reaper is chosen; for medium-sized land holdings, self-propelled vertical conveyer reapers are preferred; and for small land holdings, manually operated vertical conveyer reapers are preferred.

(Manjunatha et al., 2008) Conducted a field performance evaluation of a vertical conveyer paddy reaper. The power reaper's actual field capacity was 0.3 ha/hr, with a field efficiency of 73% and an average operating speed of 3.2 km/h. Mechanization of harvesting activities could help to minimize the cost of paddy production.

### III. MECHANICAL MODELS OF SELF-SUFFICIENT RIDING REAPER

#### 1. Riding Reapers Machine Design

A Reapers Harvesting Machine is stressed by loads that are usually determined by the dynamic interaction of the stimulation and the Reaper. During the early stages of design, the data available for the Reaper and its subsystems may be insufficient to describe such dynamic interactions. Even in this phase, a study of the loads is required to identify a basic design. In the subsequent stage, a dynamic condition check is performed, yielding a more refined design. Based on these

considerations, the purpose of the next paragraph is to depict various load circumstances that will be useful in the initial design of structural body components. The Reapers Harvesting Machine, parked on a flat road and carrying the greatest payload feasible, is not in an extreme load condition. Nonetheless, flat road parking is interesting since the other requirements can be found by calculating the variances in relation to this example. Given the mass and the position of the center of gravity, the vertical loads acting on the front and rear axles are simply as follows: Machine mass ( $m$ ) = 250 kg,  $p = 2m$ ,  $a = 0.35m$  and  $b = 0.65m$ .

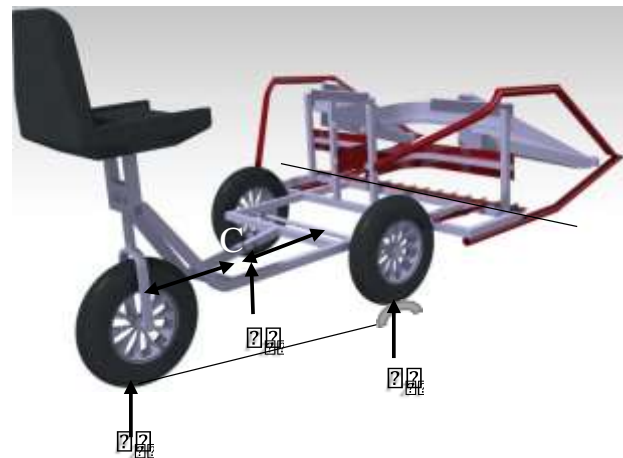


Figure 3. Parking on a curb sufficient in height to lift one wheel off the ground, leaving the automobile supported by only three wheels.

### IV. RESULT & DISCUSSION

The talks in this study will focus on the impact of harvesting technologies on total grain losses, cutting efficiency, field capacity and efficiency, energy consumption, and total cost. The prerequisites for harvesting wheat crops. The mechanization of self-prosperous riding reapers machine operation is critical to improving field capacity, field efficiency, and cutting efficiency by reducing manual work and the difficulty of gathering crops or forming bundles of goods. During crop harvesting, the cutting unit collects the harvest crop from both the left and right sides and pushes it to the machine's middle position to feed dropping or releasing to the ground in the form of

bundles. The machine is powered by a 5 kW, single cylinder, water-cooled diesel engine with a rated engine speed of 970rpm. The Reaper machine frame structure was devised and developed using the crop binding mechanism.

### **1. Principle of Self-Propelled Reapers Harvesting Machine**

The working width of the reaper machine is 120 cm, the length is 200 cm, and the machine height is 100 cm. The crop is transported vertically to the binding machinery by the finger conveyor before being delivered to the ground in bundles. During crop harvesting, the cutting unit takes the harvest crop from both the left and right sides and pushes it to the machine's central position for dropping the bundles. The machine is powered by a 5 kW, 4 cylinder, water-cooled diesel engine with a rated engine speed of 970rpm. It has a reciprocating cutter bar with a cutting width of around 120 cm that is powered by the diesel engine, which also provides two driving wheels for the front pneumatic wheels. Other systems include brakes, steering, mechanism, and power transmission, and an operator seat is offered to make the machine ride able.

## **V. CONCLUSION**

Harvesting is one of the more time-consuming and labor-intensive agricultural processes. Self-propelled riding reapers machines can be used successfully for speedy and cost-effective harvesting of wheat and rice crops, as well as to alleviate peak labor shortages during harvest. The machine can be controlled by a single person. The frame along with the other components of the reaper machine are built of angle iron, square bar, flat bar, and pipe. The materials include both standard and manufactured components that are used in the machine mentioned above. Working width of the reaper machine. 120 cm and the total length of the reaper machines are 200 cm and 125 cm, respectively. The cut crop material was bundled by the gathering equipment and left on the field. During crop harvesting, the cutting unit collects the harvest crop from both the left and right sides and pushes it to the device's middle position for

dropping or releasing to the ground in the form of bundles. The machine is powered by a 5 kW, single cylinder, water-cooled diesel engine with a rated engine speed of 970rpm. This self-propelled reaper moves at a forward speed of 2.54 m/s. The field capacity is 0.306 ha/hour, respectively. The needed manpower for harvesting one hectare of wheat and rice reaper harvesting field operation is two man-hours per ha. The amount of fuel required to completely fill the tank after harvesting the plot was measured to determine the amount of fuel consumed for reaping the test plot, which was 1.17 l/h. Before beginning the harvesting process in the test plot, the reaper's fuel tank was filled to full capacity

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